MICROCANONICAL, CANONICAL, AND GRAND CANONICAL DISTRIBUTIONS

Contents

1	Microcanonical distribution	2
2	$\Omega(E)$ of the ideal gas	4
3	Some morals from the ideal gas	9
4	Canonical distribution of a subsystem	11
5	Canonical and grand canonical distribution for the ideal gas	16
6	Canonical distribution for the general case	22
7	Equivalence of ensembles	25

1 Microcanonical distribution

We recall from the previous lectures

• **Phase space volume** for a system of N identical particles:

$$d\Gamma = \frac{d^3 \mathbf{q}_1 \dots d^3 \mathbf{q}_N d^3 \mathbf{p}_1 \dots d^3 \mathbf{p}_N}{N! h^{3N}}$$
(1)

(Lebesgue measure suitably normalized)

- **Energy surface** Γ_E , specified by H(x) = E.
- **Energy shell** of thickness $\delta E \ll E$, i.e.,

$$\Gamma_{E,\delta E} = \{ x \in \Gamma : E \le \mathsf{H}(x) \le E + \delta E \}.$$
 (2)

(System confined in Λ ⊂ ℝ³ of finite volume.) Microcanonical distribution

$$\mathbb{P}_{E,\Delta E}\left\{A\right\} = \frac{|A \cap \Gamma_{E,\delta E}|}{|\Gamma_{E,\delta E}|}, \quad A \text{ subset of } \Gamma, \qquad (3)$$

(Lebesgue measure restricted to the shell of constant energy and normalized to the volume of the shell).

• Microcanonical partition function or density of states

$$\Omega(E) = \int \delta\left(E - \mathsf{H}(x)\right) d\Gamma$$
(4)

(volume of Γ_E).

• Volume of the energy shell

$$|\Gamma_{E,\delta E}| = \Omega(E)\delta E$$
(5)

• Volume of $\Gamma_{\leq E} = \{x \in \Gamma | \mathsf{H} \leq E\}$

$$\Gamma(E) = \int_{\mathsf{H} \le E} d\Gamma = \int^{E} \Omega(E) dE$$
(6)

whence

$$\Omega(E) = \frac{d\Gamma(E)}{dE}.$$
(7)

• average of quantity Y = Y(x):

$$\mathbb{E}\{\mathbf{Y}\} = \frac{1}{\Omega(E)} \int_{\Gamma} \mathbf{Y}(x) \delta\left(E - \mathbf{H}(x)\right) d\Gamma = \frac{1}{\Omega(E)} \frac{d}{dE} \int_{\mathbf{H}(x) \le E} \mathbf{Y}(x) d\Gamma$$
(8)

2 $\Omega(E)$ of the ideal gas

 $N \gg 1$ particles in a vessel Λ of volume $|\Lambda| = V$,

$$\mathsf{H}(q,p) = \frac{p^2}{2m} = \sum_{i=1}^{N} \frac{|\mathbf{p}_i|^2}{2m}, \quad \Gamma_E : \sum_{i=1}^{N} \frac{|\mathbf{p}_i|^2}{2m} = E, \quad \mathbf{p}_i \in \Lambda.$$
$$\Gamma_{\leq E} = \left[\text{sphere in } \dim = 3N \text{ of radius } R = \sqrt{2mE} \right] \times V^N$$

Thus (recalling (1))

$$\Gamma(E) = |\Gamma_{\leq E}| = c_{3N} (2mE)^{3N/2} \frac{V^N}{h^{3N} N!},$$
(9)

where

$$C_n = \frac{\pi^{n/2}}{(n/2)!}, \quad (n/2)! = \Gamma\left(\frac{n}{2}+1\right), \quad \Gamma(x+1) = \int_0^\infty t^x e^{-t} dt$$

is the volume of the unit sphere in n dimensions. Whence,

$$\Omega(E) = \frac{d\Gamma_{\Lambda}(E)}{dE} = C_{3N} \frac{3N}{2} (2m) (2mE)^{(3N/2)-1} \frac{V^N}{h^{3N} N!}$$
(10)

and

$$|\Gamma_{E,\delta E}| = \Omega(E)\delta E \tag{11}$$

Since $N \sim 10^{23}$ we are interested in the asymptotic of $|\Gamma_{E,\delta E}|$ for N and V large such that

$$N/V = n = \text{const.}, \quad E/N = \varepsilon = \text{const.}$$

To this end, we introduce the function

$$S(E, N, V) = \log |\Gamma_{E, \delta E}|$$
(12)

N.B. At this stage this "*S*-function" is only introduced for mathematical convenience, and no thermodynamic meaning is attributed to it; later on we shall see that it provides the microscopic interpretation of the thermodynamic entropy at equilibrium.

Asymptotic estimate We have

$$S(E, N, V) = \log\left(\frac{\pi^{3N/2}}{(3N/2)!} \frac{V^N}{h^{3N}N!}\right) + \left(\frac{3N}{2} - 1\right)\log(2mE) + \log\left(\frac{3N}{2} 2m\delta E\right)$$
$$= \log\left(\frac{\pi^{3N/2}}{(3N/2)!} \frac{V^N}{h^{3N}N!}\right) + \frac{3N}{2}\log(2mE) + O(\log N)$$

We now use Stirling formula $\log N! = N \log N - N + O(\log N)$ to evaluate the first term

$$I = \frac{3N}{2} \log \frac{\pi}{h^2} + \log \left(\frac{V^N}{(3N/2)^{3N/2} e^{-3N/2} N^N e^{-N}} \right) + O(\log N)$$
$$= \frac{3N}{2} \log \frac{\pi}{h^2} + N \log \frac{V}{N} - \frac{3N}{2} \log \frac{3N}{2} + \frac{5}{2}N + O(\log N)$$

whence

$$S(E, N, V) = N \log \left[\frac{V}{N} \left(\frac{4\pi m}{3h^2} \frac{E}{N} \right)^{3/2} \right] + \frac{5}{2}N + O(\log N)$$

$$= N \left\{ \log \left[v \left(\frac{4\pi m}{3h^2} \varepsilon \right)^{3/2} \right] + \frac{5}{2} \right\} + O(\log N), \quad v = V/N, \quad \varepsilon = E/N$$

$$= N \underbrace{\left(\log v + \frac{3}{2} \log \varepsilon + \frac{3}{2} \log \frac{4\pi m}{3h^2} + \frac{5}{2} \right)}_{s(v,\varepsilon)} + O(\log N)$$
(13)

Note that (negleting logarithmic corrections) S(E, N, V) is estensive, i.e.,

$$S(E, N, V) = Ns(v, \varepsilon).$$
(14)

We have thus established the following proposition:

Proposition 1

The volume of the energy shell of the ideal gas of N particles is asymp-

totically

$$|\Gamma_{E,\delta E}| \asymp e^{S(N,V,E)} = e^{Ns(v,\varepsilon)}$$

where

$$v = V/N, \ \varepsilon = E/N$$

and

$$s(v,\varepsilon) = N\left(\log v + \frac{3}{2}\log\varepsilon + \frac{3}{2}\log\frac{4\pi m}{3h^2} + \frac{5}{2}\right)$$

Note that the dependence on δE drops out and that we would have obtained the same result for the volume of $\Gamma_{\leq E}$ (exercise). So we have

$$\Omega(E) \asymp \Gamma(E) \asymp e^{Ns(v,\varepsilon)}$$
(15)

N.B " \asymp " expresses an equality relationship on a logarithmic scale: $a_n \asymp b_n$ means that

$$\lim_{n \to \infty} \frac{1}{n} \log a_n = \lim_{n \to \infty} \frac{1}{n} \log b_n.$$

3 Some morals from the ideal gas

- For the ideal gas $\Omega(E)$ is positive and monotonically increasing for E > 0. This is expected to be true also for general systems and has been proven for many realistic models.
- Also the specific estimate

$$|\Gamma_{E,\delta E}| \asymp e^{Ns(v,\varepsilon)} \tag{16}$$

is expected to be true also for general systems and has been proven for many realistic models.

• More precisely, one considers the description of a large system in the limit $E, N, V, \Lambda \to \infty$ such that $E/N \to e, N/V \to n$ with e, n finite. This is called the *thermodynamic limit*. In particular, one wishes to show that existence of the limit

$$\frac{\log |\Gamma_{E,\delta E}|}{N} \to s(e,n) \,,$$

where s(e, n) is of course different from that of the ideal gas, but like the that of the ideal gas is *convex*. This is in general difficult to prove [explain] (after 1960-70 for "almost" realistic systems).

• (16) is basically a *large deviations* estimate with *s* the rate function. Roughly, the reason is the following:

The energy is fluctuating in the interval $[E, E + \delta E]$ (random variable) and is of the form

$$\mathsf{H}(x) = \sum_k \mathsf{E}_k(x)$$

where

$$\mathsf{E}_k(x) = \mathsf{H}_k(x_k) + \sum_{i \neq k} V(q_i - q_k)$$

The probability distribution of $\frac{1}{N}\mathsf{H}(x)$,

$$\frac{1}{\left|\Gamma_{E,\delta E}\right|}\left|\Gamma_{\frac{1}{N}\mathsf{H}(x)=y}\right|$$

is exptected to concentrate exponentially with N on the mean value e

4 Canonical distribution of a subsystem

We wish to compute the limit distribution of the state of the particles in any finite subvolume Δ_a .



Splitting

$$\Lambda = \Delta_a + \Delta_b \quad (\Delta_b = \Lambda \setminus \Delta_a), \quad x = (x_a, x_b)$$

where x_a is the state of the particle in Δ_a and x_b the state of the particles in Δ_b . In the microcanonical ensemble are constants the total number of particle

$$\mathsf{N}(x) = \mathsf{N}_a(x_a) + \mathsf{N}_b(x_b) = N$$

and the total energy

$$\mathsf{H}(x) = \mathsf{H}_a(x_a) + \mathsf{H}_b(x_b) + \mathsf{V}(x_a, x_b) = E \,.$$

We shall assume that the interaction energy is negligible so that

$$\mathsf{H}(x) = \mathsf{H}_a(x_a) + \mathsf{H}_b(x_b) = E$$

Understanding the splitting For any $x = (x_a, ..., x_N)$, let S(x) be the subset of $\{1, 2, ..., N\}$ for which $x_i \in \Delta_a$. Then x can then be split into

$$\mathsf{X}_{a}(x) = (\mathsf{X}_{a_{1}}(x), \dots, \mathsf{X}_{a_{\mathsf{N}_{a}}(x)}) \text{ and } \mathsf{X}_{b}(x) = (\mathsf{X}_{b_{1}}(x), \dots, \mathsf{X}_{b_{\mathsf{N}_{b}}(x)}),$$

where the X_{1i} and the X_{2i} are placed in the same order as in x. (For example, if $x = (x_1, x_2, x_3, x_4, x_5)$ and $S(x) = \{2, 3, 5\}$ then $X_a(x) = (x_2, x_3, x_5)$ and $X_b(x) = (x_2, x_4)$).

Calculation of the average of any quantity in Δ_a If $Y_a = f(X_a, N_a)$ is any symmetric function of the state of the particles in Δ_a , then its average can be computed as follows:

$$\begin{split} \int_{\mathsf{H} \leq E} f\left(\mathsf{X}_{a}(x), \mathsf{N}_{a}(x)\right) d\Gamma &= \sum_{S} \int_{\mathsf{H} \leq E, \mathsf{S}(x) = S} f\left(\mathsf{X}_{a}(x), |S|\right) d\Gamma \\ &= \sum_{S} \int_{\mathsf{H} \leq E} f\left(X_{a}(x), |S|\right) \frac{dx}{N!} \\ &= \sum_{S} \int_{\mathsf{H}_{a}(x_{a}) + \mathsf{H}_{b}(x_{b}) \leq E} f\left(x_{a}, |S|\right) \frac{dx_{a} dx_{b}}{N!} \\ &= \sum_{N_{a}} \binom{N}{N_{a}} \int \frac{1}{N!} f(x_{a}, N_{a}) dx_{a} \int_{\mathsf{H}_{b} \leq E - \mathsf{H}_{a}} dx_{b} \\ &= \sum_{N_{a}} \int f(x_{a}, N_{a}) \frac{dx_{a}}{N_{a}!} \int_{\mathsf{H}_{b} \leq E - \mathsf{H}_{a}} \frac{dx_{b}}{(N - N_{a})!} \\ &= \sum_{N_{a}} \int f(x_{a}, N_{a}) \Gamma_{b}(E - \mathsf{H}_{a}(x_{a}), N - N_{a}) \frac{dx_{a}}{N_{a}!} \end{split}$$

Thus

$$\mathbb{E}\{\mathsf{Y}_a\} = \frac{1}{\Omega(E,N)} \sum_{N_a} \int f(x_a, N_a) \Omega_b(E - \mathsf{H}_a(x_a), N - N_a) \frac{dx_a}{N_a!}$$

We hence see that the probability of having N_a particles in Δ_a with state x_a has probability density

$$\frac{\Omega_b(E - \mathsf{H}_a(x_a), N - N_a)}{\Omega(E, N)} \frac{dx_a}{N_a!}$$

Consider now the function $f(x_a, N_a) = 1$ iff $H_a(x_a) \leq E_a$ and $N_a = N_a$. Then

$$\mathbb{P}\left\{\mathsf{H}_{a} \leq E_{a}, \mathsf{N}_{a} = N_{a}\right\} = \frac{1}{\Omega(E, N)} \int_{\mathsf{H}_{a}(x_{a}) \leq E_{a}} \Omega_{b}(E - \mathsf{H}_{a}(x_{a}), N - N_{a}) \frac{dx_{a}}{N_{a}!}$$
$$= \frac{1}{\Omega(E, N)} \int_{E' \leq E_{a}} \Omega_{b}(E - H_{a}, N - N_{a}) \Omega_{a}(H_{a}, N) dH_{a}$$

so the joint density of E_a and N_a is

$$\frac{\Omega_b(E - E_a, N - N_a)\Omega_a(E, N_a)dE_a}{\Omega(E, N)}$$

From this result we see that $\Omega(E, N)$ is composed by convolution, because the total integral is one:

$$\Omega(E,N) = \sum_{N} \int \Omega_a(E_a, N_a) \Omega_b(E - E_a, N - N_a) dE_a$$
(17)

Summary:

Proposition 2

Consider a system in Λ with a m.can. distribution defined by E, N. Then if $\Lambda = \Delta_a + \Delta_b$ with $\Delta_a \cap \Delta_b = \emptyset$ and if the interaction between particles in Δ_a and Δ_b is negligible, the state (X_a, N_a) has probability distribution

$$\mathbb{P}\left\{\mathsf{X}_{a} \in dx_{a}, \mathsf{N}_{a} = N_{a}\right\} = \frac{\Omega_{b}(E - \mathsf{H}_{a}(x_{a}), N - N_{a})}{\Omega(E, N)} \frac{dx_{a}}{N_{a}!},$$

the variables H_a and N_a have distribution

$$\mathsf{P} \{ \mathsf{H}_a \in dE_a, \mathsf{N}_a = N_a \} = \frac{\Omega_b (E - E_a, N - N_a) \Omega_a (E_a, N_a)}{\Omega(E, N)} dE_a ,$$

and

$$\Omega(E,N) = \sum_{N_a} \int \Omega_a(E_a, N_a) \Omega_b(E - E_a, N - N_a) dE_a$$

5 Canonical and grand canonical distribution for the ideal gas

$$\Omega(E,N) = \frac{(2m\pi)^{3N/2}}{(3N/2)!} \quad (3N/2) \quad E^{(3N/2)-1} \quad \frac{V^N}{N!}$$

so in the limit

$$N \to \infty, \quad \frac{E}{N} \to \epsilon \quad \frac{N}{V} \to n, \quad E_a, V_a, N_a =$$
const.

we obtain¹

$$\frac{\Omega_b(E_b, N_b)}{\Omega(E, N)} \frac{dx_a}{N_a!} = \frac{dx_a}{N_a!} (2\pi m)^{-3N_a/2} \frac{(3N/2)!}{(3N_b/2)!} \frac{3N_b/2}{3N/2} \frac{E_b^{(3N_b/2)-1}}{E^{(3N/2)-1}} \frac{V_b^{N_b}}{V^N} \frac{N!}{N_b!}$$

$$\approx \frac{dx_a}{V_a} \left(V_a \right)^{N_a} \left(V_b \right)^{N_b} \left(N \right)_{(2-m_b)^{-3N_a/2}} \frac{(3N/2e)^{3N/2}}{(3N/2e)^{3N/2}} E_b^{(3N_b/2)}$$

$$\approx \frac{dx_a}{V_a^N} \left(\frac{\overline{V}}{V}\right) \left(\frac{\overline{V}}{V}\right) \left(\frac{N_a}{N_a}\right)^{(2\pi m)^{-3N_b/2}} \frac{\overline{(3N_b/2e)^{3N_b/2}}}{(3N_b/2e)^{3N_b/2}} \frac{\overline{(2\pi m)^{-3N_b/2}}}{V_a^{N_a}} \approx \frac{dx_a}{N_a!} \frac{(nV_a)^{N_a}}{N_a!} e^{-nV_a} (2\pi m)^{-3N_a/2} (3/2e)^{3N/2} (N/N_b)^{3N/2} (E_b/E)^{3N/2} (N_b/E_b)^{3N_a/2}$$

the last 3 factors tend to

$$(N/N_b)^{3N/2} = \left(1 - \frac{N_a}{N}\right)^{-3N/2} \to e^{3N_a/2}$$
$$(E_b/E)^{3N/2} = \left(1 - \frac{E_a}{E}\right)^{3N/2} \to e^{-3E_a/(2\epsilon)}$$
$$(N_b/E_b)^{3N_a/2} \to \epsilon^{-3N_a/2}$$

¹Stirling's formula : $n! = \sqrt{2\pi n} (n/e)^n$.

so the probability distribution for N_a and x_a converges to

$$\mathbb{P}_{\infty}\{\mathsf{X}_{a} \in dx_{a}, \mathsf{N}_{a} = N_{a}\} = \frac{(nV_{a})^{N_{a}}}{N_{a}!}e^{-nV_{a}} \left(\frac{4m\pi\epsilon}{3}\right)^{-3N_{a}/2} e^{-3\mathsf{H}_{a}(x_{a})/(2\epsilon)} \frac{dx_{a}}{V_{a}^{N_{a}}} \\ = \frac{(nV_{a})^{N_{a}}}{N_{a}!}e^{-nV_{a}} \left(\frac{4m\pi\epsilon}{3}\right)^{-3N_{a}/2} e^{-\frac{3}{4m\epsilon}\sum_{i=1}^{N}|\mathbf{p}_{\mathbf{a}i}|^{2}} \frac{dq_{a}dp_{a}}{V_{a}^{N_{a}}}$$

Let us now highlight the main features of the probability distribution so obtained. To this end, let us drop the indices "1" and ∞ , call Δ the finite region of volume $V = |\Delta|$, let x, N denote the state of the gas in Δ , an rewrite the above formula as

$$\mathbb{P}\left\{\mathsf{X}_{\Delta} \in d\Gamma, \mathsf{N}_{\Delta} = N\right\} = \frac{(nV)^{N}}{N!} e^{-nV} \left(\frac{4m\pi\epsilon}{3}\right)^{-3N/2} e^{-\frac{3}{4m\epsilon}\sum_{i=1}^{N}|\mathbf{p}_{i}|^{2}} \frac{dqdp}{V^{N}}$$
(18)

It gives the joint probability of having N particles in Δ in the state x=(q,p)

(a) The momenta $p = (\mathbf{p}_a, \dots, \mathbf{p}_N)$ have a normal distribution

$$\left(\frac{4m\pi\epsilon}{3}\right)^{-3N/2}e^{-\frac{3}{4m\epsilon}\sum_{i=1}^{N}|\mathbf{p}_{i}|^{2}}$$

with variance $2m\epsilon/3$, so the average kinetic energy of a particle is

$$\left\langle \frac{|\mathbf{p}_i|^2}{2m} \right\rangle = \epsilon$$

(b) By integrating out q and p one obtains the marginal distribution of N_{Δ}

$$\mathbb{P}\left\{\mathsf{N}_{\Delta}=N\right\} = \int \mathbb{P}\left\{\mathsf{X}_{\Delta}\in d\Gamma, \mathsf{N}_{\Delta}=N\right\} = \frac{(nV)^{N}}{N!}e^{-nV}$$

Thus, the positions in space form a Poisson process with density n. Hence

$$\mathbb{E}\{\mathsf{N}_{\Delta}\} = nV \equiv \overline{N}, \qquad \operatorname{Var}(\mathsf{N}_{\Delta}) = nV$$

so that

$$\mathbb{P}\left\{\mathsf{N}_{\Delta}=N\right\}=e^{-\overline{N}}\frac{\overline{N}^{N}}{N!}$$

(c) If the number of particles in Δ is fixed to have the value *N*, the conditional distribution is

$$\mathbb{P}\{\mathsf{X} \in d\Gamma | \mathsf{N}_{\Delta} = N\} = \frac{\mathbb{P}\{\mathsf{X}_{\Delta} \in d\Gamma, \mathsf{N}_{\Delta} = N\}}{\mathbb{P}\{\mathsf{N}_{\Delta} = N\}} \\
= \left(\frac{4m\pi\epsilon}{3}\right)^{-3N/2} e^{-\frac{3}{4m\epsilon}\sum_{i=1}^{N}|\mathbf{p}_{i}|^{2}} \frac{dqdp}{V^{N}} \quad (19)$$

(d) The probability formula (18) has the following form

$$\mathscr{Z}^{-1}e^{-\beta \mathsf{H}_N(x)+\beta\mu N} \frac{dx}{N!}$$
 (20)

where

$$\mathscr{Z} = e^{-\overline{N}}$$
$$\beta = \frac{3}{2\epsilon}$$
$$H_N(x) = \sum_{i=1}^{N} \frac{|\mathbf{p}_i|^2}{2m}$$
$$\mu = \frac{1}{\beta} \ln \left[\frac{\overline{N}}{V} \left(\frac{2\pi m}{\beta} \right)^{-3/2} \right]$$

(e) The probability formula (19) has the following form

$$Z^{-1}e^{-\beta \mathsf{H}_N(x)} \quad \frac{dx}{N!} \tag{21}$$

where

$$Z = \frac{V^N}{N!} \left(\frac{2\pi m}{\beta}\right)^{3N/2}$$

6 Canonical distribution for the general case

Proposition 3 (Gibbs-Boltzmann's law)

The distribution of the state of a small subsystem in a large system with finite densities of particles and energy has a probability density proportional to

$$e^{-\beta \mathsf{H}_N(x) + \beta \mu N} \frac{dx}{N!}$$
 (22)

This is a very general law which was discovered by Boltzmann. (The exponential factor is often called the B-factor.)

It is easy to verify it in the situation where we have an arbitrary system in Δ_a with a fixed no. of particles in contact with an ideal gas in Δ_b , a heat bath (that is, formula (22)). The two parts can exchange energy, but the interaction energy can be neglected. The particles in Δ_a and Δ_b need not to be of the same type. Then

$$\Gamma(E, N_a, N_b) = \int_{\mathsf{H}_a(x_a) + \mathsf{H}_b(x_b) \le E} \frac{dx_a}{N_a!} \frac{dx_b}{N_b!} = \int \frac{dx_a}{N_a!} \Gamma_b(E - \mathsf{H}_a(x_a), N_b)$$
$$= \int \Gamma_b(E - \mathsf{H}_a(x_a), N_b) \Omega_a(E_a, N_a) dE_a$$

whence

$$\Omega(E, N_a, N_b) = \int \Omega_a(E_a, N_a) \Omega_b(E - E_a, N - N_a) dE_a$$
(23)

so the probability density for X_a is proportional to

$$\Omega_b(E - \mathsf{H}_a(x_a), N - N_a) \frac{dx_a}{N_a!}$$

Since

$$\Omega_b(E_b, N_b) = K(N_b) \ E_b^{(3N_b/2)-1},$$

we see that the density is proportional to

$$(E - \mathsf{H}_{a}(x_{a}))^{3N_{b}/2-1} = (\text{const.}) \left(1 - \frac{\mathsf{H}_{a}(x_{a})}{E}\right)^{3N_{b}/2-1} \rightarrow \\ \rightarrow (\text{const.}) \ e^{-3/(2\epsilon) \ \mathsf{H}_{a}(x_{a})},$$

and hence it converges to

$$\frac{e^{-\beta \mathsf{H}_a(x_a)}}{Z} \frac{dx_a}{N_a!} , \qquad \beta = \frac{3}{2\epsilon} , \quad Z = \int e^{-\beta E_a} \Omega_a(E_a, N_a) dE_a .$$
(24)

The distribution so obtained is called *canonical* and is more important in practice than the m. can. one since very often one is interested in precisely this situation where the system is in contact with a *heath bath*.

The normalization constant

$$Z = Z_{\Lambda}(N,\beta) = \int e^{-\beta \mathsf{H}_{N}(x)} \frac{dx}{N!} = \int e^{-\beta E} \Omega(E,N) dE$$

is called the *canonical partition function*.

The exponential form means that if two systems do not interact: $H(x_a, x_b) = H_a(x_a) + H_b(x_b)$, then they are also independent:

$$e^{-\beta \mathsf{H}(x_a, x_b)} = e^{-\beta \mathsf{H}_a(x_a)} e^{-\beta \mathsf{H}_b(x_b)}$$

and this is a considerable simplification.

7 Equivalence of ensembles

In general H(x) has a distribution very sharply concentrated around its average when N is large, so **one gets the same results concerning most averages as in the m.can. ensemble where** H(x) **is fixed to this value, because the conditional distribution of** x **given that** H(x) = E**is the m.can. distribution**. (The B-factor is constant on each energy shell.)